

Three Channels Power Motor Driver

AM1229D

The AM1229D is a three-channel driver for DC motors and it integrates the Motor and Logic supply Pins. The AM1229D provides a high integrated motor-driver solution for Helicopters. The output driver block consists of two open-drain N-MOS; one H-bridge to drive motor winding and a built-in Low Dropout Linear Regulator (LDO). The built-in LDO output voltage can be used to the microcontroller (MCU), the gyroscopes (GYRO)...etc.

The AM1229D operates on a device power-supply voltage from 3.0 V to 6.5 V. CH_A can supply up to 0.8A of output continuous current and 2.0 A of output maximum current ; CH_B and CH_C can supply up to 3.0A of output continuous current and 4.0 A of output maximum current.

The AM1229D has internal shutdown function for Over-temperature protection (TSDp = 150 ° C) , Over-temperature protection recover (TSDr = 125 ° C) , Power reverse-connect protection to prevent the IC damage in any wrong using ,the CH_B/CH_C have the shutdown function for Over-current protection(I_{OCP} = 4.5 A) and the built-in LDO output voltage V_{LDO}=2.94 V °

Its package material is Pb-Free and Halogen-Free (Green) for the purpose of environmental protection and for the sustainable development of the Earth.

● Applications

- Helicopters

● Features

- 1) Surface mount package (DFN-3X3)
- 2) Built-in steady voltage output
- 3) Lower supply current
- 4) Lower VCC standby current
- 5) Lower MOSFETs On-resistance
- 6) Over-temperature protection
- 7) Over-temperature protection recover
- 8) Over-current protection (CH_B&C)

● Ordering Information

Orderable Part Number	Package	Marking
AM1229D	DFN-3X3	AM1229D

● **Absolute Maximum Ratings ($T_A=25^{\circ}\text{C}$)**

Parameter	Symbol	Limits	Unit
Supply voltage	VCC	7.0	V
CH_A Output continuous current	I _{ocont}	0.8	A
CH_A Output maximum current	I _{omax}	2.0	A
CH_B&CH_C Output continuous current	I _{ocont}	3.0	A
CH_B&CH_C Output maximum current	I _{omax}	4.0	A
Operate temperature range	T _{opr}	-40~+125	°C
Storage temperature range	T _{stg}	-40~+150	°C

● **Recommended operating conditions ($T_A = 25^{\circ}\text{C}$)**

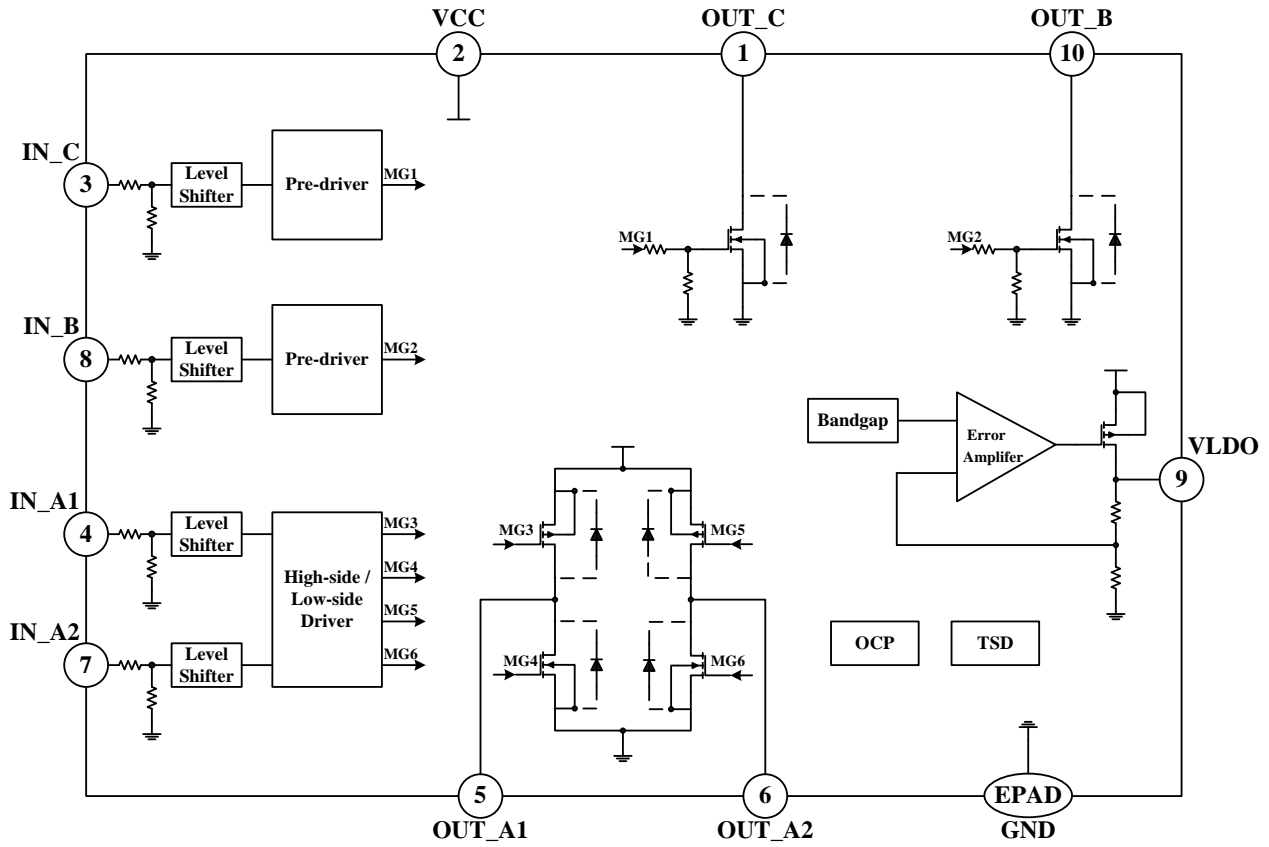
(Set the power supply voltage taking allowable dissipation into considering)

Parameter	Symbol	Min	Typ	Max	Unit
Operating supply voltage range	VCC	3.0		6.5	V
IN_AX and IN_B/C	V _{IN}	-0.3		V _{cc} +0.3	V
CH_A output current	I _{OUT}	0		0.8	A
CH_B/C output current	I _{OUT}	0		3.0	A
Externally applied PWM frequency	f _{PWM}	0.02		65	KHz

● Electrical Characteristics (Unless otherwise specified, $T_A = 25^{\circ}\text{C}$, $V_{CC}=5\text{V}$)

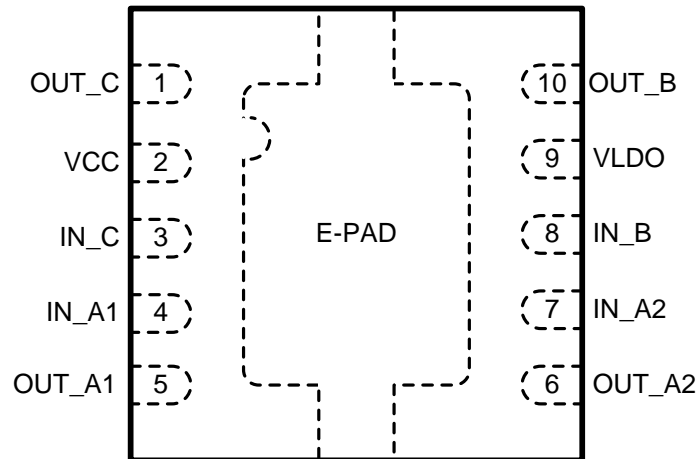
Parameter	Symbol	Limit			Unit	Conditions
		Min	Typ	Max		
Power Supplies						
VCC Supply current	I_{CC}		25		μA	Input signal IN_AX=H, IN_/B/C= L, No load on OUT_A/B/C & VLDO terminal
VCC Standby current	I_{STB}		5	10	μA	Input signal IN_AX/B/C=L, No load on OUT_A/B/C & VLDO terminal
PWM Inputs						
Input H level voltage	V_{PWH}	2.5		V_{CC}	V	
Input L level voltage	V_{PWL}	0		0.7	V	
Input H level current	I_{PWH}		30		μA	$V_{CC} = 5\text{V}$, $V_{IN} = 3\text{V}$
Input frequency	F_{PWM}	0.02		65	KHz	
Input pulldown resistance	R_{IPD}		100		K Ω	
Output						
CH_A on-resistance	$R_{ds(on)}$		0.72		Ω	$I_O = 200\text{mA}$ Upper and Lower total
CH_B on-resistance	$R_{ds(on)}$		0.12		Ω	$I_O = 600\text{mA}$ Lower total
CH_C on-resistance	$R_{ds(on)}$		0.12		Ω	$I_O = 600\text{mA}$ Lower total
TSD Protections						
Thermal shutdown protection	TSDp		150		$^{\circ}\text{C}$	
Thermal shutdown release	TSDr		125		$^{\circ}\text{C}$	
LDO parameter						
LDO output voltage	V_{LDO}	2.85	2.94	3.03	V	$I_{Load} = 35\text{mA}$
Output Load transient	ΔV_{RL}			25	mV	$I_{Load} = 0\sim 35\text{mA}$
Output Line transient	ΔV_{VCC}			50	mV	$(V_{CC}=3.2\text{v}\sim 6.5\text{v}), I_{Load}=35\text{mA}$

● Block Diagram



● **Pin configuration**

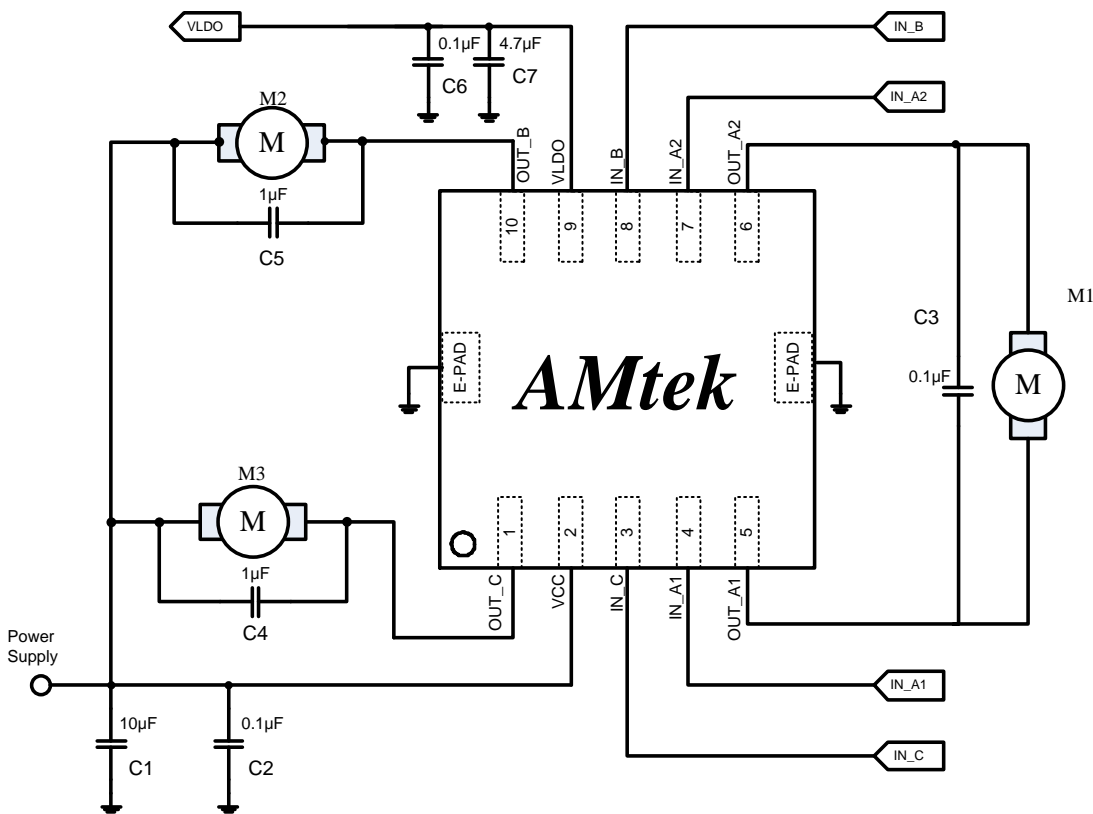
TOP VIEW



● **Pin Description**

PIN No	Pin Name	I/O	Description
1	OUT_C	O	CH_C Output terminal
2	VCC	-	Power input
3	IN_C	I	CH_C Input signal
4	IN_A1	I	CH_A Input positive signal
5	OUT_A1	O	CH_A Output positive terminal
6	OUT_A2	O	CH_A Output negative terminal
7	IN_A2	I	CH_A Input negative signal
8	IN_B	I	CH_B Input signal
9	VLDO	O	LDO Output terminal
10	OUT_B	O	CH_B Output terminal
11	E-PAD	-	Ground

● Application



● Circuit Descriptions

The functional description of capacitors on the application circuits:

- I. C1, C2: V_{CC} input capacitor:
 - 1) The capacitor can reduce the power spike from the motor, to avoid the IC being directly damaged by the peak voltage. It also can stabilize the V_{CC} voltage and decay its ripples.
 - 2) The capacitor can offer motor the compensated power in motor start running.
 - 3) The capacitor value depends on the value of the V_{CC} and motor loading. In general, a $10\mu\text{F}$ capacitor is enough in low voltage power (V_{CC}). If the large voltage power or a heavy loading motor is used, a larger capacitor should be chosen.
 - 4) On the PCB configuration, the C1&C2 must be mounted as close as possible to V_{CC} (PIN2).

- II. C3, C4, C5: The across-motor capacitor:
 - 1) The C3 capacitors can reduce the power spike of motor in start running. A $0.1\mu\text{F}$ capacitor is recommended.
 - 2) The C4&C5 capacitors can reduce the power spike of motor in start running. A $1\mu\text{F}$ capacitor is recommended.

- III. C6, C7: The LDO output capacitor
 - 1) The capacitor can reduce the voltage spike and It also can stabilize the VLDO voltage and decay its ripples.

● **Input Logic Description**

Function truth table of CH_A

IN_A1	IN_A2	OUT_A1	OUT_A2	Mode
L	L	L	L	Stop
L	H	L	H	Forward
H	L	H	L	Reverse
H	H	L	L	Stop/Brake

Function truth table of CH_B/CH_C

IN_B/IN_C	OUT_B/OUT_C	Mode
L	H	Open
H	L	Active

※Low standby current function when IN_A1 = IN_A2 = IN_B = IN_C = Low level

● Operating Mode Descriptions

1) H-Bridge basic operation mode

a) Forward mode

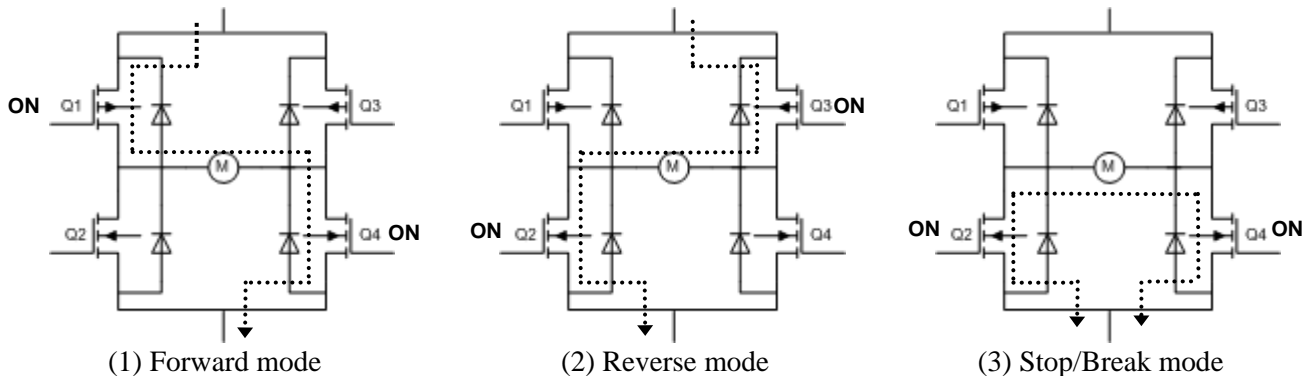
Definition : When $IN_A1=H$, $IN_A2=L$, then $OUT_A1=H$, $OUT_A2=L$

b) Reverse mode

Definition : When $IN_A1=L$, $IN_A2=H$, then $OUT_A1=L$, $OUT_A2=H$

c) Stop/Break mode

Definition : When $IN_A1=IN_A2=L$ or H , then $OUT_A1=OUT_A2=L$



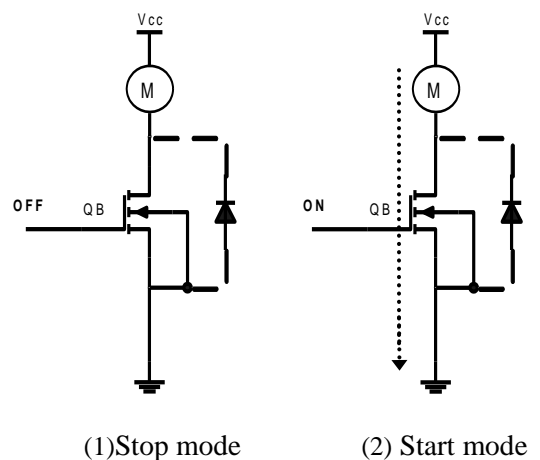
2) CH_B/C basic operation mode

a) Stop mode

Definition : When $IN_B/C = L$, then $OUT_B/C = H$

b) Start mode

Definition : When $IN_B/C = H$, then $OUT_B/C = L$



● Protection Descriptions

1) Over-temperature protection

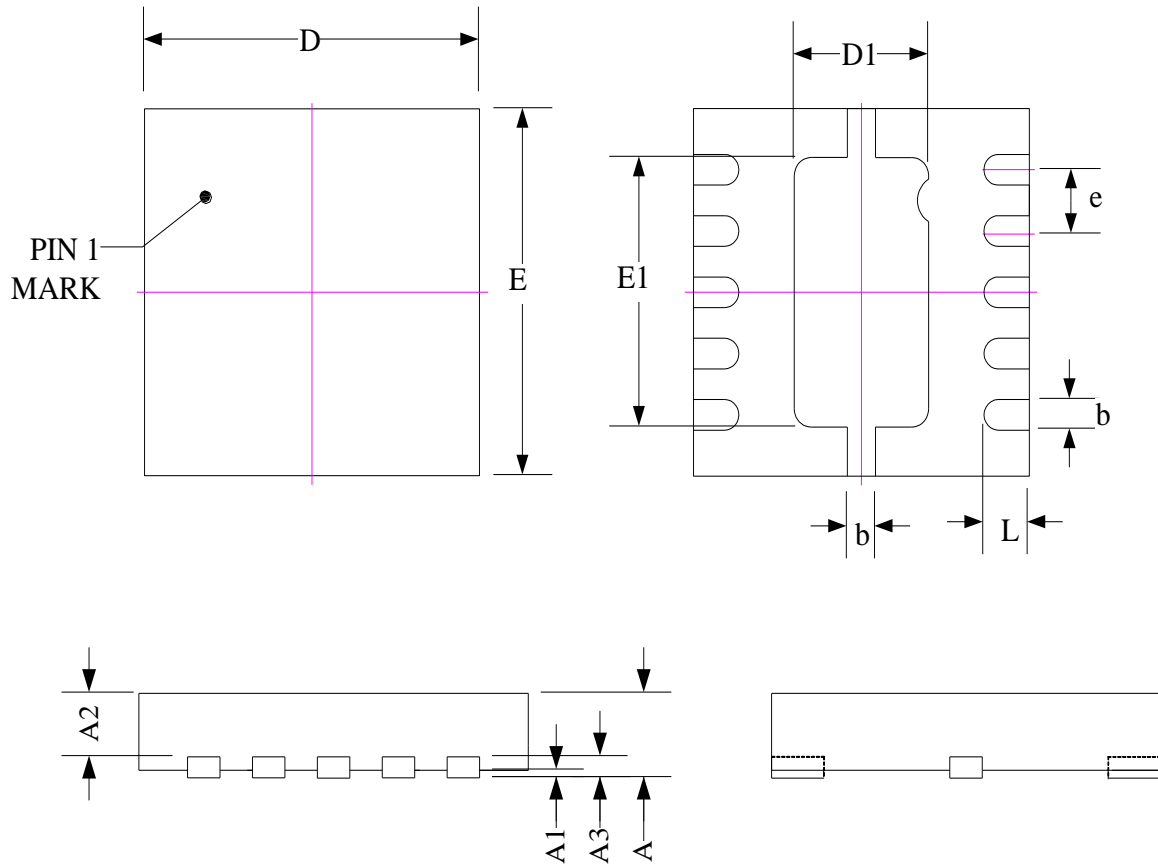
If the IC junction temperature exceeds $150^{\circ}C$ (Typ), the internal over-temperature protection circuits will be triggered and all the FETs in H-bridge are disabled to ensure the safety of customers' products. If it falls to $125^{\circ}C$ (Typ), the IC resumes automatically.

2) Over-current protection (OCP)

While the CH_B/C passes through a large current, $4.5A$ (Typ), the internal OCP circuits will be triggered and entry a protection mode of auto-recover to avoid damage in IC and EE system of device.

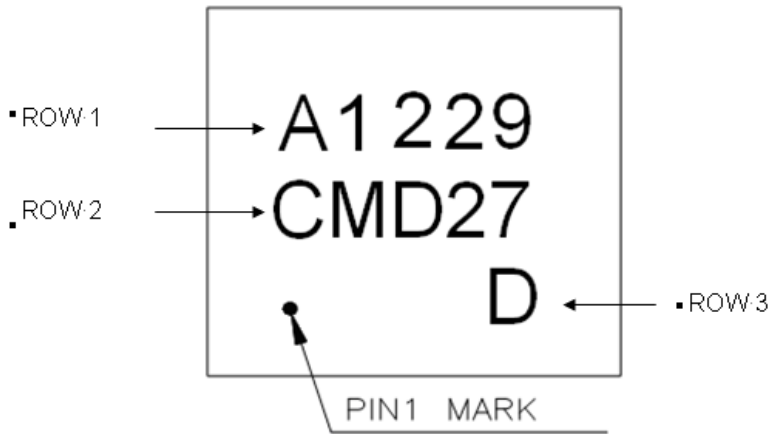
● Packaging outline --- DFN-3X3

Unit : mm



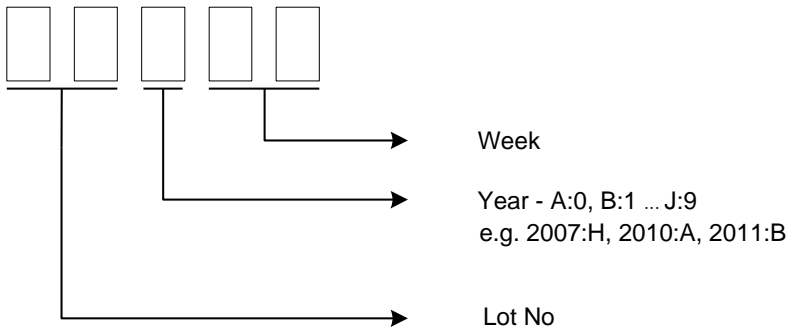
SYMBOL	MILLIMETERS		INCHES	
	Min.	Max.	Min.	Max.
A	-	0.60	-	0.023
A1	-	0.05	-	0.002
A2	-	0.43	-	0.017
A3	0.15 REF		0.006 REF	
b	0.18	0.30	0.007	0.012
D/E	3.00 BSC		0.118 BSC	
D1	1.10	1.30	0.043	0.051
E1	2.10	2.30	0.083	0.091
L	0.30	0.50	0.012	0.020
e	0.5 BSC		0.020 BSC	

● **Marking Identification**



Row 1
A1229

Row 2
Date & Lot number



Row 3
D for DFN